Final Report:
Single Hand Manual Drive Wheelchair

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Abstract

The single hand manual drive wheelchair will be built so that the operator will be able to control the wheelchair solely by the right hand. The purpose of the project is to allow the client to have more freedom of movement in a lightweight, portable wheelchair, even though she cannot control movement in her left hand. The team will make modifications to an existing manual wheelchair in order to incorporate a single hand mechanical drive device. The team will research existing products on the market that allow for wheelchair patients to control their chairs using one hand. The wheelchair must be no wider than 32 inches (standard doorway) and collapse to less than 12 inches for ease of portability.

It will be necessary to incorporate a safe braking system to the wheelchair so that the client can stop easily. There are many different types of braking systems on the market, so the team will have to decide which one is best for use on the single hand manual drive wheelchair. Some braking systems require use with both hands, which will not be feasible for this project. The team must find a system that allows use with just one hand, or make modifications to an existing product.

The budget for this project is approximately $1000. The purchase of the manual wheelchair will be the most expensive item in the budget. The team will be purchasing additional items including braking systems and one-arm drive components that will be modifications to the wheelchair. These additional parts will also be included into the budget. Safety is also a concern, so the team will purchase safety harnesses to be attached to the wheelchair so that the client can safely travel in the family’s minivan.

1. Introduction

1.1 Background

Danielle Giroux is an eleven year old girl living with cerebral palsy. Cerebral palsy is a condition that involves brain and nervous system functions. It is caused by injuries or abnormalities in the brain that occur as the baby grows in the womb up until two years of age, when the baby’s brain is still developing.

Danielle lives with her parents and two siblings in Tolland, CT. She attends Tolland middle school and rides the bus to and from school every day. Danielle is very bright and is very outgoing. Danielle’s parents Dave and Suzanne Giroux contacted the University of Connecticut Biomedical Engineering department to inquire about possible design projects that could benefit Danielle’s daily life.

Danielle also has certain physical limitations that inhibit her from controlling movement in her left hand. This limited motor control makes it difficult to propel and maneuver a manual wheelchair. The patient also recently had back surgery, which makes it difficult for her to cross her right arm over the rest of her body.
1.2 Purpose of the Project

The purpose of this project is to design a more user-friendly wheelchair for our client who suffers from limited mobility. It is very difficult for the patient to move her manual wheelchair because she must make several movements with just one arm, crossing over her body to control the left side. The single hand manual wheelchair will be designed so that it is functional using only the operator’s right hand. The patient uses a motorized wheelchair to move around her school, but the heaviness and bulkiness make it difficult for use within the home. Danielle and her family would like to use the manual wheelchair within the house or in other informal settings.

Danielle and her family are worried about safety of this wheelchair. It is important to design a wheelchair that will incorporate a braking system so that the patient can easily slow down and stop without hesitation. A quick braking system will be applied to the wheelchair so that the patient can easily stop on command. The final product will allow the patient to stop simply using her right hand.

1.3 Previous Work Done by Others

1.3.1 Products

There is a product that is manufactured by Complete Medical called a One Arm Drive for Viper manual wheelchairs (model #10960RD), which is a replacement armrail mechanism that can be applied for patients who have limited mobility. Basically, this product is a replacement part in which the system can replace both wheels on an existing manual wheelchair. This product is sold for $256.36 online at http://makemeheal.com. Figure 1 below demonstrates this product.

![Figure 1: One Arm Drive for Viper manual wheelchair](image)

The company Southwest Medical specializes in a product line called Quickie Wheelchairs, along with a set of replacement parts to go along with their products. The company offers complete sets of one-arm drive replacements for
their wheelchairs. These complete sets can be purchased and modified to fit onto an existing Quickie Wheelchair. An example of these replacement kits can be found in Figure 2 below. It is possible for the group to find an existing set of one-arm drive wheelchair parts, such as the one seen in Figure 2, and assemble them to an existing manual wheelchair. The price of this kit costs anywhere between $680 to $900, depending on the model of wheelchair.

![Figure 2: Replacement parts for one-arm drive](image)

It is necessary for the single hand manual wheelchair to have a braking mechanism so that the operator can easily stop. The ADI company manufactures a set of disc brakes for manual wheelchairs that allow the user to simply push a lever to slow down. It’s called the Variable Lever Disc Brake system and is easily controlled with one hand only, compared to other systems that must be operated with both hands. Figure 3 below shows an operator applying the brake using the simple hand lever. A set of disc brakes surround the center of the wheel and when the hand brake is applied, the discs close to stop wheel movement. The price of this system was not listed on the manufacturer’s website, but can be approximated at about $250.

![Figure 3: ADI disc brake hand lever](image)
1.3.2 Patent Search Results

The single-hand manual drive wheelchair assembly patent is owned by David M. Counts of Quickie Designs Inc. (US Patent #5306035). This innovative design shows dual armrails on one side of the wheelchair that function to propel each of the wheels. These two armrails rotate about a common wheel axis. One armrail controls the wheel on the right side, while the other controls the wheel on the left. Additionally, there is a locking mechanism that is controlled by the operator that will allow simultaneous rotation of both wheels in order to propel the wheelchair in a straight direction. A representation of this invention can be found in Figure 5 below.

![Figure 5: Representation of Self-hand manual drive wheelchair (US Patent #5306035)](image)

1.4 Additional Requirements

The wheelchair must be aesthetically pleasing to the patient and others in her environment. The family has requested that it not look “robotic” with all sorts of metal contraptions, but that it has a soft feel and look to it. This will ensure comfort for the patient and so that it looks like any other standard wheelchair. Extra padding and covering will be put in specific places to give a softer feel to the device.

The group must obtain their own manual wheelchair for this project. The specific model does not matter, as long as it is sturdy, collapses for the patient, and is able to fit through a doorway measuring no more than 32 inches wide. The wheelchair will have a mechanical device that allows the operator to use solely their right hand to propel and steer.

The wheelchair must have appropriate seating to support the patient in an upright position. Many manual wheelchairs contain seats that do not provide proper posture for the operator. Often times, the patient does not have proper back support in these types of wheelchairs. The group would take existing hip guides and heat support from one of
Danielle’s wheelchairs and attach them to the single hand manual driven wheelchair. The group will keep in contact with Danielle’s physical therapist to ensure that the new wheelchair will provide adequate support for the patient.

The wheelchair must also be able to attach to the patient’s minivan via a buckle system. This harness system will allow the patient to properly be strapped into the van in case of a motor vehicle accident. The finished product must have four tie-down locations on the wheelchair (2 in front and 2 in back), along with a vest support to secure the patient. This vest support will consist of a harness that is tied to the wheelchair and goes over the patient’s shoulders to secure their body in place. The width of the inside of the van is approximately 30 inches, which allows for plenty of room for any standard-sized wheelchair. Additionally, the client’s family would like the chair to take up as little space as possible when not in use. Therefore, it is important to design a wheelchair that will be able to collapse and be as portable as possible.

After discussing all of these constraints with the client, the team was able to create a chart detailing all of the specifications for this project. An outline of these quantitative specifications can be found in Appendix Section 12.1.

2 Project Design

2.1 Introduction

The team was able to take all of these requirements into consideration and develop three alternative designs for the single hand manual drive wheelchair. The first alternative design uses a device that attaches to the right side of the wheelchair and functions using a pumping action with the right arm. In order to apply the brakes, the user simply pulls back on the device, which will rest against the wheel to prevent movement. The second and third alternative designs use the one arm drive system discussed earlier in this report (Figure 1). The only difference between these systems is the braking mechanisms. The second alternative design uses a set of disc brakes, whereas the third alternative design uses a set of hand brakes, similar to those in a bicycle. For the case of all these alternative designs, the team will be obtaining their own lightweight, portable wheelchair and assembling a separate one arm drive system to it.

2.1.1 Alternative Design 1

This design of the single hand manual driven wheelchair will consist of a one-arm lever drive system. A lever one arm drive (OAD) system consists of a lever mounted to the front caster area of the wheelchair with linkages back to the rear wheel of the chair. The lever drive has a forward, neutral, and reverse setting and when the lever is pushed forward and back while in gear the chair moves in the direction chosen. The neutral setting is used when the wheelchair is being pushed by a caregiver.
To slow, stop or park a one arm drive wheelchair the client will pull the lever as far back as possible, while in neutral, to lock the wheel locks. To steer a lever style one arm drive, the user turns the lever in the direction they want to go and the caster steers the chair in that direction. The caster on the lever side of the wheelchair does not freely turn left and right as it would on a conventional drive manual wheelchair and its direction is constantly adjusted by the user's manipulation of the lever while the chair is in motion. The lever can be "pumped" during a turn regardless of the direction chosen to maintain speed and momentum.

The design will be implemented on the client’s current wheelchair. Since the client has no use of her left hand, it will be assembled on the right side of her current manual wheelchair. The existing wheel and axle sleeve will be removed and replaced with an axle sleeve that will work with the one armed lever system. The existing wheel is also replaced with a wheel suited for the one arm drive wheelchair.

![Figure 5: One Arm Drive Lever System](image)

### 2.1.2 Alternative Design 2

The second alternative design relies on the purchase of a one arm drive assembly as shown earlier in Figure 1. The team would use the One Arm Drive manufactured by Complete Medical, which costs approximately $260. The group will assemble the One Arm Drive to the manual wheelchair in order to ensure that it can be controlled using one arm. The One Arm Drive for manual wheelchairs consists of a replacement arm rail mechanism that can be applied for patients who have limited mobility. Basically, this product is a replacement part which replaces both wheels on an existing manual wheelchair.

The One Arm Drive system includes double hand-rims on one side (in this case, on the right) of the wheelchair that control the rear wheels on both sides. The larger, outer hand-rim controls the wheel on that side of the wheelchair and the inner hand-rim controls the wheel on the opposite side. The hand-rim that
controls the wheel on the opposite side is connected to the wheel by a scissor-like bar mechanism. To propel the wheelchair in a straight line, Danielle will grip both hand-rims at once. To turn the wheelchair, she will exert more pushing pressure on one hand-rim or the other.

A second aspect to this design is the inclusion of a proper braking mechanism, which is very important for the safety of the operator while using the wheelchair. The group will design a mechanism that can be operated with only the right hand via a lever system. A set of disc brakes will be purchased (if possible) or designed and created in the machine shop and affixed to the wheelchair’s wheels (See Figure 6 for example). A challenge to this design will be keeping the existing One-Arm Drive mechanism in place when attaching a braking system.

![Figure 6 - Example of a disc brake](image)

Since this design consists of multiple preexisting systems, the challenge will be adapting them to work together and fit whatever manual wheelchair we end up using. We also need to make sure that the resulting one arm drive wheelchair is easy enough for our client to use, and make modifications if it is not.

Finally, there are a few other minor details to this design. First, we will need to put extra padding on the one-arm driven wheelchair that we design to give Danielle the correct amount of support and comfort. The final product of our design also must be visually pleasing and not too “robotic” looking. These details are discussed in the third alternative design, and will be incorporated into whichever design we choose.

### 2.1.3 Alternative Design 3

The third alternative design will incorporate the one-arm drive similar to that shown in the second alternative design, though it will have a different braking mechanism. The team will start by obtaining their own manual wheelchair and purchasing the item in Figure 1 called the One Arm Drive for Viper manual wheelchairs (model #10960RD), manufactured by Complete Medical. Similar to the second alternative design, the team will attach this system to the manual
wheelchair. This device will allow the client to control the wheelchair using only her right hand.

The team will incorporate a braking mechanism into the wheelchair so that it can be easily stopped upon command. The team may find that a disc brake system discussed in the second design idea is too difficult and costly, especially if the wheels must be replaced. In this case, the team will seek alternate methods, such as the use of a single-handed brake similar to the braking mechanism on a standard bicycle. However, most of the ones that are out on the market do not allow the operator to control them with a single hand. The group will purchase a set of hand brakes similar to the one in Figure 7 and attach them to the wheelchair so that the operator can stop movement of both wheels using just one hand. This may require some minor adjustments so that the cables are redirected to perform as desired. The handbrakes will function using a set of rubber pads that close around the tires of the wheelchair to stop movement. When the brakes are applied, the cable will tighten, causing the rubber clamps to close around the tire. The operator can simply release the tension to allow movement again.

![Figure 7: Example of simple hand brake mechanism](image)

The comfort and visual aesthetics of the wheelchair are also important to the client. The team will use plastic cable wraps and foam padding to cover any cables and objects on the wheelchair that may seem abstract or hindering its visual appearance. The chair is supposed to have a soft feel and not look so robotic with different mechanical objects protruding out.

The wheelchair must have proper support for the client, so it will be necessary to obtain head supports, hip guides, and pummel. Figure 8 below shows examples of the head rest and hip guides that will be used for this project. The group will work closely with Danielle’s physical therapist in order to discuss proper seating position for adequate back and neck support. The group will be purchasing the supports and attaching them to the wheelchair according to the recommendations from Danielle’s physical therapist.
The wheelchair must have proper restraint system for use in a motor vehicle. It is necessary for there to be straps in place so that the operator can be safely secured in the family’s minivan. The team will purchase a set of safety harnesses and attach them to the single hand manual drive wheelchair. These straps will be set in place to properly restrain the subject in case of a motor vehicle accident. The team will use the existing restraint system in the family’s minivan to tie down the wheels of the chair to prevent movement while the vehicle is in motion. The family already has a lifting mechanism and tie down system in place for the minivan, so the only modification that must be made will be the addition of a safety harness for the subject’s body. This harness must be adjustable so that the subject can loosen and tighten it at their desire.

The final product will function so that the operator the wheelchair will be able to propel, steer, and stop the device using only their right hand. There will be proper safety features in place to allow the chair to be stopped when desired and for safe use in a motor vehicle. Once the product is complete, the team will let Danielle test it out and make any adjustments as needed.

2.2 Optimal Design

2.2.1 Introduction

The team has begun designing the single hand manual wheelchair for a client who does not have motor control in their left hand. The client has expressed a need for an easier way to navigate her wheelchair using only one hand, while still being able to control how fast it goes and which way it steers. There were three alternative designs that the team took into careful consideration when selecting the optimal design. The first design incorporates a one arm lever system that can be used in a pumping fashion to move the chair in forward and reverse directions with the turn of a switch. The client’s specifications called for a braking system to be built into the wheelchair so that the client can easily stop
movement on command. The braking system involved with this design involves simply switching the gears into neutral and pulling back on the lever arm to stop movement. The second and third designs both incorporated a double-railed wheel setup on the right side of the wheelchair so that the client can propel the chair forward by spinning the rim associated with the respective wheel. There will be two rails on the right side—one rail controlling movement of the right wheel and another rail controlling movement of the left wheel. A gear box will allow the client to switch between control of a single wheel or control of both wheels in order to steer the wheelchair in different directions.

The fall back of these designs is that a separate braking mechanism must be installed. Since the second and third alternative designs incorporated the same double-rail movement system, they had different braking mechanisms. The second design incorporated a set of disc brakes into the system that are similar to those in a motor vehicle. The disc brakes would be located within the rim of the wheel and around the axle. When the client applied the brakes, the discs would press against the wheel to cause friction in order to prevent movement. The third alternative design incorporated a set of hand brakes similar to what is seen on a standard bicycle. The hand brakes would function using a set of rubber pads that attach to a clamp around the tires. When the client desired to slow down or stop, they would squeeze a lever that would create tension in a wire connected to the brake pads. This would cause the clamp holding the brake pads to close, and the pads would create friction on the tire to prevent movement.

The group discussed these three alternative designs and determined that the first one using the one arm lever system would be best for a number of reasons. One of the advantages of this system is that it is easy to control and steer. There is only one lever that sticks out on the right side that allows the client to control movement of the wheelchair with ease. Figure 5 above shows a sample representation of this one arm drive lever mechanism. Another advantage over the other designs is that the existing system already includes a braking mechanism. Therefore, it will be less costly and more time effective for the group to use this system because they will not have to look into purchasing a separate braking system to attach to the final product.

One of the advantages of this project is that each of the designs includes a one hand drive mechanism that has been built and is on the market for sale. The two systems that have been discussed are both available for purchase and use with specific wheelchair models only. However, one of the complications of this project is that these wheelchair models are not able to collapse. There are no one hand drive mechanisms out on the market that are capable to use with an existing folding wheelchair. One of the specifications that the client requires is that the wheelchair has the ability to collapse so that it can be transported and stored easily. Therefore, the challenge of this design project is to take the existing one hand drive lever system and modify it to fit a folding manual wheelchair.
2.2.2 Conventional Folding Wheelchairs

There are many different types of wheelchairs, ranging from lightweight, portable, heavy-duty, manual, powered, folding, sport, and reclining. These different types all have benefits over others and are for use with a variety of different purposes. The type that the group will use for this design will be a conventional folding wheelchair for the sole purpose of being lightweight and portable. The client has specified that a folding manual wheelchair is necessary for this project so that the family can easily transport it from one place to the other. An example of a traditional folding wheelchair is shown in Figure 9 below.

![Figure 9: Example of a standard manual folding wheelchair](image)

A standard non-powered (manual) wheelchair must be controlled manually by two hands. There are two different types of manual wheelchairs, which are folding and non-folding. All standard manual wheelchairs have four wheels--two large in the back and two small in the front. The two front wheels are much smaller than the rear wheels and this is because they function for stability and are responsible for guiding the chair in the right direction when the operator makes a turn. The front wheels are able to swivel a full 360 degrees, while the rear wheels do not swivel at all. The purpose of the larger rear wheels is to allow movement of the wheelchair. Notice the large metal hand-rail in the sample wheelchair in Fig. 4. The operator must grab the hand-rail and rotate the wheels on the left and right sides of the wheelchair in order to allow the chair to move forward. The operator turns by simply stopping rotation of the wheel on the side of the wheelchair where they wish to turn.

The client for this project does not have motor control in their left hand, which makes it very difficult to control movement on the left side of a standard manual wheelchair. This makes it extremely difficult for the client to propel the chair forward in a straight direction, or to steer to the left or right. The client normally uses her manual wheelchair within the home because it is easier to control in a smaller environment when compared to a power wheelchair. The
The purpose of this project is to adapt a mechanism that can allow the client to move and steer a manual wheelchair using only one hand. Another requirement from the client is that the one-hand drive wheelchair be able to fold so that the family can easily transport it when necessary.

2.2.3 Invacare Cyclical Lever Drive

In order to produce a final product that will be functional, the team will design a system that incorporates all the specifications and requirements to meet the client’s needs. The team will pull from multiple resources in order to satisfy the needs of the final product. The optimal design for this wheelchair involves the use of a product manufactured by the Invacare Company. Invacare is a medical supply company that produces wheelchairs and wheelchair accessories for clients with disabilities. The system that the team will be purchasing will be the Cyclical Lever Drive (CLD) mechanism that functions as a lever to control movement of the wheelchair using a single hand. Figure 10 below shows an example of the CLD system. This system is manufactured specifically to fit Invacare 9000 Series wheelchairs for clients like Danielle who have loss of motor control in their left hand.

The way the system functions is that it incorporates a lever arm that must be pumped in a forward motion to allow the wheelchair to move. The lever is attached to a transmission drive system, which is attached to the axle of the rear wheels. The client can control what direction they would like their chair to move—forward or reverse—by simply switching the gear in the transmission. Movement of the wheelchair can be stopped by pulling the lever arm back to prevent movement of the wheels. Further description of each of the components will be discussed further on. The CLD system is available for purchase from a number of different local retailers.
One of the advantages of the CLD system is that it functions using only one hand. The purpose of this project is to design a system that can be applied to a standard manual wheelchair for the client to control using only their right hand. The CLD mechanism also has a built in braking system that functions to stop movement of the wheelchair upon command. This is one of the safety features that the client had recommended for the final product. There are also a few drawbacks to the CLD system as well. For instance, the system does not fit any standard manual wheelchair—it will only fit the Invacare 9000 Series wheelchairs, represented in Fig. 10. This makes it a challenge for the team to incorporate this system on any random existing manual wheelchair that the team happens to come across when searching for potential parts. The team may not find an Invacare 9000 Series wheelchair to fit their budget, which makes it a challenge to be able to apply the CLD system to any standard manual wheelchair.

Another major drawback of the Invacare CLD system is that the online specifications do not indicate whether it can be applied to a folding wheelchair. The Invacare 9000 Series wheelchair products are standard manual wheelchairs, but do not collapse for easy portability. Therefore, the team cannot use an Invacare 9000 Series wheelchair because it does not meet the specifications and needs of the client. The client has requested that the wheelchair be able to fold for easy transport and portability. The team must adapt a method to incorporate the CLD system into any standard folding wheelchair in order for this project to be successful. The most challenging portion of this project will be designing a method for the existing single arm drive system to fit to any standard folding wheelchair. The team cannot simply follow the detailed instructions for installing the one arm drive system because those instructions will be specific to the Invacare 9000 Series wheelchair. In order to be successful, the team must use the installation instructions as a guide to fitting the one arm system on another manual wheelchair that is able to fold.

### 2.2.4 Drive Arm Assembly

The CLD system is broken down into many different components, each serving a purpose in the overall functionality of the wheelchair. The first major component is the arm assembly and Fig. 11 below shows a diagram of the basic setup. Basically, there is a two foot long handle that attaches to the fork of the front right wheel to control the steering and forward and reverse movements of the wheelchair. The drive arm functions as the main method of control for the client. The arm is moved back in forth in a pumping action in order to propel the wheelchair forward. With each pump, the lever system moves a set of gears attached to the axle, and this provides movement to the rear wheels. The arm is attached to the front wheel via a rotating mechanism, which allows the client to steer the direction of the wheelchair by turning the lever arm left or right. The client will also be able to adjust the height of the lever arm by simply unscrewing
a nut that holds it in position. The lever arm will be able to slide up and down to
the client’s desired height and can be securely tightened in place. This will allow
the client to setup the arm assembly in a comfortable position in order to
minimize discomfort while the wheelchair is in use.

Figure 11: CLD Drive Arm Assembly

2.2.5 Fork and Steering Assembly

The second major component is the fork and steering mechanism. Figure
12 below shows a diagram of the basic fork and steering assembly. These
components are responsible for holding together the drive arm and the front right
wheel. The fork is a common part that attaches wheels because it has two prongs
that go on each side of the wheel with an axle holding it together in the middle.
This piece is made of aluminum or stainless steel and must be strong enough to
support the weight of the wheelchair without falling apart. At the base of the
drive arm (and the top of the fork assembly) there is a rotating fork stem and
caster headtube that are essential for the 360 degree rotation of the wheel. The
fork stem is placed within the caster headtube and the hex nut prevents the fork
stem from being removed. The fork stem is free to rotate within the caster
headtube with very little friction. This fork assembly is attached to the lever arm
component and this entire assembly makes the wheelchair able to turn in any
direction by applying simple movement to the lever arm.
2.2.6 Rear Wheel and Axle

The third set of components of the one arm drive system are the rear wheels and axle. Figure 13 below shows a diagram representing how these components function as the lever arm is pumped. When the operator of the wheelchair desires to move forward, they will pump the lever arm and this will move the transmission assembly and transmission rear hub. The motion of these parts will essentially spin the rear wheel hub spokes and axle, which will ultimately spin the right and left wheels. The rear wheels are connected to the same rotating axle, so both wheels will rotate together at the same speed.

The most difficult challenge in this project is to design a one hand drive system that will be able to attach to a standard folding wheelchair. The existing CLD system does not have the capability of easily attaching to a folding wheelchair, which makes it difficult to use this type of mechanism. It is necessary for the team to design a modification to this existing CLD system in order to apply it to a standard folding wheelchair according to the client’s specifications. The most logical way to go about this is to create a mechanism by which the rear axle can fold. If we recall the folding manual wheelchair in Fig. 9, we can observe the folding mechanism and try to adapt a similar system for use in the single hand manual drive wheelchair. Traditional manual wheelchairs have a rear axle that splits in the middle and is able to collapse on itself. This axle is separated in the middle by a joint that is locked in place until the user decides to
fold the wheelchair. Once the user decides to fold the wheelchair, they must unlatch the mechanism holding the axle joint in place and the wheelchair is easily able to collapse for portability and storage. Figure 14 shows a representation of this folding axle mechanism that the team will use to modify the existing CLD system.

Figure 14: Example of folding hinge that will be used on one arm wheelchair

When designing the single hand manual wheelchair, the group will use a similar folding hinge mechanism and adapt it to the CLD system. This is the easiest way for the team to cover all the specifications, which include the ability of the wheelchair to move with only one hand, stop on command, and fold for easy portability and storage. The team will use the existing CLD rear wheel axle and modify it so that it can collapse when the wheelchair is in folded position. This will be done by applying a simple hinge in the middle of the axle so that the two sides fold on top of one another. This method is almost an exact replication of what is seen in existing manual wheelchairs, however there is a set of rear wheel hub spokes and slot that the team must work around and take into consideration when coming up with a design. This is definitely the most difficult aspect of the design that the group faces for this project.

2.2.7 Transmission

The transmission component of the wheelchair design is responsible for allowing the operator to change gears between forward, neutral, and reverse movement. This piece comes with the CLD system and is part of the lower portion of the lever arm. It basically attaches to the wheelchair side frame via a set of screws and this is what ultimately holds the control arm in place. The transmission will function using a small lever that protrudes out the top. This lever will be accessible to the client on the right side of the wheelchair. There are three different gears as mentioned before--forward, neutral, and reverse. When
the client desires to move in the forward direction, they will engage the gear using the small lever. The same process is necessary for moving in the reverse direction as well. Figure 15 below demonstrates the basic setup of the transmission system.

One of the things that is important to take into consideration is how difficult is it for the client to be able to switch gears. The shifting arm is a very simple setup and should not require a lot of energy to move. The pumping action of the control arm on the wheelchair is also another concern because it requires that the client make several pumping motions back and forth to move the wheelchair in any direction. The group will work closely with the client to ensure that they are able to operate the wheelchair with ease and that it does not require a high degree of physical strain to use.

![Figure 15: CLD Transmission and Gear Lever Assembly](image)

**2.2.8 Ability to Disengage**

One of the best features of this wheelchair is the ability to disengage the gears. This is really beneficial if the operator decides they do not want to control the wheelchair by themselves. This feature allows the ability for someone to disengage the gears so that they can manually push the wheelchair from behind. The disengaging mechanism is something that functions using a spring and pin. The bottom of the lever arm contains a piece that attaches to the front wheels like what is shown in Fig. 16 below. The pin can simply be removed from its holder on the front wheel to allow the wheelchair to be disengaged from the control arm setup.
Another important feature is the ability to lock the rear wheels in place. This is useful if the operator wants to prevent movement of the wheelchair if they are getting in or out. This is an important safety feature because if the wheelchair moves while the client is sitting down or standing up then it may cause the client to slip and get injured. The wheelchair locking mechanism is shown in Fig. 17 below. The functionality of this design allows a lever to be turned that presses a brake pad against the tires to prevent movement. This lever operates with a simple turn and can lock the wheel in place. There are two wheel locks—one for each side of the wheelchair to attach to the large rear wheels. The small front wheels do not have locking mechanisms.

Safety of the one arm drive wheelchair is a very important concern. The group is taking into account a braking mechanism that will allow the client to easily stop the wheelchair on command. Some of the alternative designs discussed ideas about disc brakes and hand brakes for the one arm manual drive.
wheelchair. However, these ideas needed separate mechanical drive and braking mechanisms. The CLD system incorporates its own braking mechanism within the design. In order to apply the brakes, the operator simply pulls back on the arm drive lever. This motion can even be performed when the chair is in forward or reverse gears. An image representing the braking system and brake pads is shown in Fig. 18 below. When the operator pulls back on the lever arm, it will press the brake pad against the rubber tire, which will hinder movement of the wheels. The advantage of using this system is that there are very little mechanical pieces or wires sticking out. If the team were to incorporate a hand brake system similar to that seen in bicycles, there would be many metal wires sticking out and running from the front to the back of the wheelchair. The existing system shown in Fig. 18 eliminates all these wires and large contraptions and keeps the design relatively simple.

![Figure 18: CLD braking mechanism](image)

### 2.2.11 Safety Features

The team will also be taking into account the safety features used in a restraint system for a motor vehicle. The client’s minivan already has the necessary wheelchair tie downs for the wheels, however the team must design the buckle system for the seat on the wheelchair. Figure 19 shows a typical image of a client riding in a wheelchair inside a motor vehicle. Both the front and rear wheels are safely secured to the floor of the minivan so that the wheelchair cannot move. The team will attach a restraint system to the wheelchair to ensure that the client is secured while riding in the family’s minivan. There will be a strap that goes across the client’s chest and lap that will buckle into place just like a standard seat belt in a car.
2.2.12 Proper Support

One of the most important features of this wheelchair is the support system for the client. The team will be working closely with Danielle’s physical therapist to ensure that the wheelchair provides proper posture and support. The team will invest in padding including hip guides, head rest, and pummel so that they can ensure the client gets the support she needs. Figure 20 shows an example of a headrest that will be applied to the single hand manual wheelchair. The headrest will be approximately 8 inches tall, by 5 inches wide. It will be made out of soft foam padding and will be positioned behind the client’s head according to the recommendations from her physical therapist.

Figure 20: Example of headrest (left) and actual headrest (right)

Figure 21 shows the exact pummel that the team will be using for the single hand manual drive wheelchair. The pummel goes at the base of the seat between the client’s legs to make sure that their legs do not cross. The device will be attached to the wheelchair using the screw holes on the left side. It is necessary to incorporate a hinge system so that the pummel can be folded down to allow the client to easily enter or exit the wheelchair.

Figure 21: Pummel used on Single Hand Manual Drive Wheelchair
Figure 22 shows an example of footrests that will be used on the wheelchair. The team will discuss the proper seating position with Danielle’s physical therapist to make sure these hip guides are aligned in the correct position.

![Figure 22: Example of footrests for client support](image)

### 2.2.13 Detachable Seat

One of the most important features of the single hand drive manual wheelchair is the ability of it to fold for easy portability and storage. This task will be very difficult with all the support padding in place, so the team will design a chair that can be easily removed. This chair will be set into the wheelchair and will contain all the necessary padding and support, including hip guides, head rest, and pummel. The chair will not be able to fold when the seat is in place. Once the seat is unbuckled from the wheelchair and removed, it will be able to collapse. The chair will sit in place via a buckle system. When the operator desires to use the wheelchair, they will unfold it and set the seat into position. A set of buckle straps will be clipped into place to secure the seat in position on the wheelchair. The team will purchase a seat similar to the one shown in Fig. 23 below. This is a seat used in a motor vehicle, but something like this has holes in the side to allow straps to easily attach to the wheelchair.

![Figure 23: Example of detachable bucket seat](image)
3 Realistic Constraints

There are many physical constraints that come into play with the design of this single hand manual drive system. For example, the team must consider the realistic constraints associated with the economic, environmental, sustainability, manufacturability, ethical, social, political, and health and safety concerns. The team must make sure that this design is feasible and that the final product is beneficial for the client without hindering their safety or wasting money.

The group will take economic concerns into consideration when designing the single hand manual drive wheelchair. The purpose of the project is to make a wheelchair that can be fully functional using only the right hand, however the group does not want to design a product that will be way too expensive. In other words, it is necessary that the costs don’t outweigh the benefits. In industry, engineers design products, but they will not sell if the production costs are too high. The company would simply lose money out of the manufacturing of the product. The same concept applies to our single hand manual drive wheelchair.

Another constraint that the team faces are the environmental impacts of the wheelchair. The team will not be using any motorized components, so they are not worried about pollutants that could be harmful to the environment. The team must be careful with what types of materials they are using and what kind of impact they will have on the environment. If the team were using dangerous chemicals to construct the wheelchair, then there would be serious impacts on the environment and safety of the client and team members. However, the team will not be using any potentially dangerous chemicals or pollutants in the fabrication of this product, so it is not necessary to be particularly concerned about the impact on the environment.

The manufacturability of the product is a large concern that the team must take into consideration when designing the wheelchair. The team does not want to design something that will be extremely difficult to produce or hard to use. The design should be kept as simple as possible, and consideration into every minute detail is critical to ensure that the final product is successful. The constraints of the project should be within reason so that the team is not trying to build something that is close to the impossible. The feasibility of the project is something that is critical both in the senior design course and in real world industry.

The sustainability of the product is very important as well because the team does not want to create something that will fall apart after a short period of use. The final product should be strong and sturdy and able to support years of use without falling to pieces. The group will ensure to double check all mechanical parts on the wheelchair before turning it over to the client to make sure that everything is safe and that bolts and screws are tightened in place. Should the unexpected happen and something to go wrong, the group will provide an instruction manual for the client to perform simple repairs and preventative maintenance.

The social concerns have to do with how the client interacts with her environment and the people around her. The client has specified that the wheelchair not look so robotic and that special padding or paint be used to cover large protruding parts if necessary. The team will keep the mechanical parts within reason so that the wheelchair will not stand out in the client’s environment. The family would like the wheelchair to
look like any other ordinary wheelchair to not draw a large amount of attention. The group also does not want to design something that will be too difficult for the client to use in her environment. The lever arm system must be a very simple design so that the client can control it with ease. If the lever arm were too difficult to use, it would defeat the purpose of making the wheelchair to begin with.

Health and safety concerns are by far the most important aspect of the single arm manual wheelchair design. The team will take many precautions into consideration when designing the final product to ensure complete operator safety. The first safety component is the use of seat restraints. These can be used for when the client is in a motor vehicle so that they properly restrain the operator in case of a motor vehicle accident. Another health and safety component is the position of the seating in the wheelchair. The team will work closely with the client’s physical therapist to ensure that the right hip guides, head rest, and pummel are used and positioned correctly so that they do not harm the client’s health. The third health and safety concern is the ability to stop the wheelchair on command. The chair will have a built-in braking mechanism so that the operator will simply have to pull back on the one arm drive mechanism and the wheelchair will stop. This will function using a set of brake pads that will enclose on the tire to stop movement. Another safety feature is the ability to lock the wheels. This will be useful if the client is getting into or out of the wheelchair and will prevent the wheelchair from moving during the process.

4 Safety Issues

The team will take into account many safety and health concerns when designing the one arm drive manual wheelchair. For example, many of the possible safety concerns necessary to address are components that have to do with electronics, mechanical pieces, biological hazards, decontaminants, chemical hazards, radiation, thermal factors, biocompatibility, and host reaction to materials. Fortunately, there are no materials in this project that are being inserted into the human body, so the team does not need to worry about biocompatibility and how the body will react to foreign substances. There are also no electrical concerns associated with this project because the team will not include any electronics in the design of the one arm drive manual wheelchair. However, there are always potential safety concerns with the mechanical pieces of the wheelchair and the possibility of someone pinching their hand or fingers in a moving component. The concerns are very minimal with the design of this single hand manual drive wheelchair, but it should be noted that it is always possible for it to happen. The team has addressed this issue by using an existing one hand manual drive system that has already been tested against these types of hazards. The rotating mechanical pieces are located underneath the wheelchair and are out of the way from any potential hazard. In order for someone to pinch their fingers, they would literally have to have their hand under the wheelchair while it is in use. Therefore, the chances of injury are very low due to mechanical components based on the location of the moving pieces under the wheelchair.
The team must be careful with what types of materials are used for the wheelchair. The team will not be using anything that is radioactive or conducts a lot of thermal energy that could be dangerous in any way to the client. Again, the client’s health and safety is the number one concern for this project. The team will use standard metals like aluminum, steel, or titanium that are strong and reliable and are harmless to the client in terms of chemical or radioactive exposure.

5 Impact of Engineering Solutions

The engineering solution to this problem is not an extremely difficult matter. The team will take an existing product out on the market and adapt it to fit the client’s purposes. The global impact to the engineering solution is that the world might see a new way to design the traditional manual wheelchair. Manual wheelchairs have always been made to operate with two hands, but it’s possible that in the future they will be designed similar to the one the team is building for Danielle. The world could see a change in how wheelchairs function in order to provide client’s like Danielle with an easier way to get around. This type of design does not have any long term influences on the economy. If the design were ever put into industry, it may perhaps be modified in the future to be less costly to produce. This would allow the company to make more money by keeping production costs low and market value high. This design has very little environmental impacts because it does not contain any radioactive or toxic chemicals that may degrade or corrode to have a negative impact on the environment. The wheelchair will be made from strong steel or aluminum components that do not have any negative impacts on the environment. The team would have to take precautions if they were working with hazardous materials that could cause potential safety and health implications. The overall societal influence that this design has is very small in terms of the entire society. However, if we were to take into account the different that it makes to the client, the impact that it has on her ability to interact with society is phenomenal.

6 Life-Long Learning

The team has learned a lot through the design of the one hand manual drive wheelchair. Before beginning this project, the team never knew that such a system existed on the market. The group has been exploring many different braking options and has learned the difference between hand brakes and disc brakes based on how they function. Both types are made to stop movement of the wheels to slow down the wheelchair’s speed, but they work differently in many ways. Disc brakes are more difficult to apply to this type of wheelchair when compared to hand brakes. The downside is that hand brakes are harder for the client to use. The team was able to find a system that allows the arm drive and brake system to be combined together for easy use. The brake system acts similar to hand brakes where there is a brake pad that rubs against the tire to prevent movement. However, since it is incorporated into the hand drive mechanism, it is easier to use because all that must be done is that the operator pulls back on the arm drive when they desire to slow down. The most important thing the team has
learned about is the condition of cerebral palsy and what sort of implications it has on the client’s mobility. The team is helping to improve the life of someone with disabilities through the design of the single hand drive manual wheelchair.

7 Budget and Timeline

7.1 Budget

For the single-hand manual drive wheelchair, the group will be purchasing their own portable wheelchair to use and make modifications to. Ideally, the team would use one similar to the Viper Lightweight Wheelchair as described earlier, which costs about $380 online. It is possible to find one of these that is used and would be cheaper than purchasing brand new.

The team will use the One-Arm Drive manufactured by Complete Medical, or a similar design, which costs approximately $260. The group will assemble the One-Arm Drive to the Viper Lightweight Wheelchair in order to ensure that it can be controlled using one arm. The team may decide to use a similar system to this, which will be about the same price range.

The team must also take into consideration costs of disc brakes or hand brakes. Disc brakes are the more expensive option, but are much easier for use with a single hand. If the team is worried about costs of disc brakes, they might be able to purchase a set of hand brakes and make modifications to them to allow single-hand use. For now, the team will estimate the cost of the disc brakes to be approximately $250.

It is also necessary to take into consideration costs of seat support. The team is assuming that the Giroux family does not have extra head rests, hip guides, or pummel and that they will need to be purchased for attachment to the wheelchair. The cost of these can be estimated around $100. The team must also take into consideration the cost of enhancing the aesthetic looks of the wheelchair. Additional padding or paint may need to be purchased and can be estimated at about $30. Table 1 below represents a budget for the single hand manual drive wheelchair.

Table 1: Estimated budget for single hand manual drive wheelchair

<table>
<thead>
<tr>
<th>Item</th>
<th>Cost</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lightweight Folding Wheelchair</td>
<td>$30</td>
</tr>
<tr>
<td>One-Arm Drive System</td>
<td>$70</td>
</tr>
<tr>
<td>Headrest/Footrest</td>
<td>$10</td>
</tr>
<tr>
<td>Specialty Seating</td>
<td>$10</td>
</tr>
<tr>
<td>Safety Harness</td>
<td>$5</td>
</tr>
<tr>
<td><strong>Total</strong></td>
<td><strong>$125</strong></td>
</tr>
</tbody>
</table>
7.2 Timeline

The team was able to come up with a list of several tasks using Microsoft Project. These tasks are needed to complete the project and can be found in Table 2 below.

<table>
<thead>
<tr>
<th>Task Name</th>
<th>Duration</th>
<th>Start</th>
<th>Finish</th>
<th>Team Member(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Go to NEAT to look at available parts/accessories</td>
<td>1 day</td>
<td>Mon 10/31/11</td>
<td>Mon 10/31/11</td>
<td>All</td>
</tr>
<tr>
<td>meet with client to discuss optimal design and sign off for approval</td>
<td>1 day</td>
<td>Sun 10/30/11</td>
<td>Sun 10/30/11</td>
<td>All</td>
</tr>
<tr>
<td>research OAD assembly instructions online</td>
<td>2 days</td>
<td>Wed 11/2/11</td>
<td>Thu 11/3/11</td>
<td>Jordan</td>
</tr>
<tr>
<td>locate parts list to ensure team has all necessary bolts and pieces for OAD system</td>
<td>1 day</td>
<td>Wed 11/2/11</td>
<td>Wed 11/2/11</td>
<td>Jordan</td>
</tr>
<tr>
<td>research and purchase alternative removable seats</td>
<td>5 days</td>
<td>Sun 11/13/11</td>
<td>Thu 11/17/11</td>
<td>Leah</td>
</tr>
<tr>
<td>research and purchase seating elements (restraint system and supports)</td>
<td>2 days</td>
<td>Sun 10/30/11</td>
<td>Mon 10/31/11</td>
<td>Kayla</td>
</tr>
<tr>
<td>contact and meet with physical therapist to discuss proper seating position</td>
<td>21 days</td>
<td>Wed 11/2/11</td>
<td>Tue 11/22/11</td>
<td>Jordan</td>
</tr>
<tr>
<td>attach drive arm assembly of OAD system</td>
<td>7 days</td>
<td>Sun 11/6/11</td>
<td>Sat 11/12/11</td>
<td>Kayla, Leah</td>
</tr>
<tr>
<td>remove existing front right wheel assembly</td>
<td>1 day</td>
<td>Sun 11/13/11</td>
<td>Sun 11/13/11</td>
<td>Kayla, Leah</td>
</tr>
<tr>
<td>install new OAD fork assembly</td>
<td>6 days</td>
<td>Mon 11/14/11</td>
<td>Sat 11/19/11</td>
<td>Jordan</td>
</tr>
<tr>
<td>remove rear wheel and install new OAD axle assembly</td>
<td>7 days</td>
<td>Sun 11/27/11</td>
<td>Sat 12/3/11</td>
<td>All</td>
</tr>
<tr>
<td>attach OAD transmission assembly to chair between drive arm + transmission</td>
<td>7 days</td>
<td>Sun 12/4/11</td>
<td>Sat 12/10/11</td>
<td>Kayla</td>
</tr>
<tr>
<td>test wheelchair mechanics of OAD to make sure system is fully functional for client</td>
<td>1 day</td>
<td>Sat 12/10/11</td>
<td>Sat 12/10/11</td>
<td>Leah</td>
</tr>
<tr>
<td>rework wheelchair brakes and locking mechanism</td>
<td>7 days</td>
<td>Sun 1/22/12</td>
<td>Sat 1/28/12</td>
<td>Jordan</td>
</tr>
<tr>
<td>attach seating supports to wheelchair according to recommendations by PT</td>
<td>7 days</td>
<td>Sun 1/29/12</td>
<td>Sat 2/4/12</td>
<td>All</td>
</tr>
<tr>
<td>apply restraint system to wheelchair</td>
<td>4 days</td>
<td>Sun 2/5/12</td>
<td>Wed 2/8/12</td>
<td>Kayla</td>
</tr>
<tr>
<td>Task</td>
<td>Duration</td>
<td>Start Date</td>
<td>End Date</td>
<td>Responsible</td>
</tr>
<tr>
<td>----------------------------------------------------------------------</td>
<td>----------</td>
<td>--------------</td>
<td>------------</td>
<td>-------------</td>
</tr>
<tr>
<td>bring wheelchair to client’s house to test restraint in motor vehicle</td>
<td>1 day</td>
<td>Mon 2/13/12</td>
<td>Mon 2/13/12</td>
<td>All</td>
</tr>
<tr>
<td>allow client to test functionality of OAD system and comfort in chair (make adjustments as necessary)</td>
<td>7 days</td>
<td>Mon 2/13/12</td>
<td>Sun 2/19/12</td>
<td>All</td>
</tr>
<tr>
<td>adjust height of drive arm to fit client</td>
<td>3 days</td>
<td>Tue 2/14/12</td>
<td>Thu 2/16/12</td>
<td>Leah</td>
</tr>
<tr>
<td>prepare for client demonstration (clean wheelchair, touch up paint, and check for loose bolts)</td>
<td>21 days</td>
<td>Sun 3/11/12</td>
<td>Sat 3/31/12</td>
<td>All</td>
</tr>
<tr>
<td>create instruction manual for client</td>
<td>26 days</td>
<td>Sun 4/1/12</td>
<td>Thu 4/26/12</td>
<td>All</td>
</tr>
<tr>
<td>allow client to test final product</td>
<td>1 day</td>
<td>Sun 4/1/12</td>
<td>Sun 4/1/12</td>
<td>All</td>
</tr>
<tr>
<td>make adjustments to final product as indicated by client</td>
<td>6 days</td>
<td>Sat 4/21/12</td>
<td>Thu 4/26/12</td>
<td>Jordan</td>
</tr>
</tbody>
</table>

8 Team Members Contributions to the Project

8.1 Team Member 1

Our first team member, Jordan, contributed to this project by visiting the client at her home in Tolland and discussing the specifications of the project with her and her family. Jordan also was responsible for writing one of the three alternative designs, as well as most of the reports for the one arm drive wheelchair throughout the semester. Our entire team, including Jordan, went to NEAT Marketplace in Hartford to purchase all the wheelchair parts and accessories. Figure 24 below shows pictures of the wheelchair and one arm drive system that were purchased from NEAT. The team was able to attach the one arm drive to the right side of the wheelchair and next semester they will focus on the proper seating position. Jordan has been responsible for keeping in close contact with the client’s physical therapist and also making sure the team’s website is up to date.

Figure 24: Wheelchair frame and complete one arm drive assembly
8.2 Team Member 2

Our second team member, Leah, contributed to this project by visiting the client at their home in Tolland to discuss the project specifications with her and her family. Leah also contributed by creating the second of three alternative designs for the one arm drive wheelchair. She also created most of the Solidworks diagrams for the alternative and optimal designs. Leah was able to come to NEAT marketplace with the rest of the team to purchase the wheelchair and accessories. The most extensive part of this project involved attachment of the one arm drive to the wheelchair. Leah was responsible for most of the work involved with the assembly of these components.

8.3 Team Member 3

Our third team member, Kayla, was responsible for also going to NEAT marketplace to pick up wheelchair parts and accessories and visiting the client at her home in Tolland. Kayla came up with the third alternative design for this project and was responsible for creating Solidworks diagrams to show how the wheelchair will operate. Kayla also worked on the assembly of the one arm drive component to the wheelchair frame. She contributed by keeping our budget up to date and was responsible for researching different safety restraint systems for the one arm drive wheelchair.

9 Conclusion

The completed single arm manual drive wheelchair will function to provide the patient with an accessible way to maneuver her wheelchair with one hand and with ease. The finished product will incorporate several safety features, including a braking system and safety harnesses for travel in a motor vehicle. The wheelchair will be able to easily collapse for portability and it will be lightweight.

This product will be different than any other product out on the market because it will contain several modifications to existing manual wheelchairs. There will be a mechanical one-arm device that will allow movement with a single hand. The user will turn a switch that will allow control over a specific wheel or both wheels so that they can easily turn. The final product will also be able to stop on command with the incorporation of a braking system. Additionally, the wheelchair will be patient-specific because it will include specific padding and support to allow proper posture. The team met their goal of having the one arm drive system fully attached to the wheelchair by the end of the semester.
10 References


<http://folduptables.co.uk/category/folup-chair/>.


### 11 Acknowledgements

- Dr. Enderle: Design advice and guidance
- Marek: Design advice and guidance
- Giroux Family: Provided design ideas to benefit Danielle
- NEAT Marketplace- Don: Assistance in finding parts
- Matt at Pediaflex: Danielle’s Physical Therapist
- Pete and Serge: Provided advice and materials
12 Appendix

12.1 Technical Specifications

Physical:
- Type of Wheelchair: Manual Wheelchair
- Model: Invacare 9000 Series
- Dimensions: 30” wide by 45” deep by 36” high
- Number of Tiedowns: 4 (2 Front, 2 Back)
- Safety Harnesses: Yes
- Type of OAD System: Invacare Cylindrical Lever Drive
- Attachment: Right Side

Mechanical (Wheelchair):
- Size: Width less than 32”, able to collapse
- Weight: Approximately 30 lbs
- Speed: User defined
- Power: Non-powered

Mechanical (One Arm Drive):
- Weight: 9.1 lbs
- System Capacity: 250 lbs
- Mechanism Color: black/chrome
- Installation: right or left hand
- Added width to chair: 1.5 in

Environmental:
- Operating Environment: Indoor/Outdoor

Safety:
- Tie-downs to secure wheelchair to vehicle
- Vest support to secure patient to wheelchair
- Simple braking mechanism

Maintenance:
- Easily fixed if malfunctions
- Allows room for growth
- Able to be transported
- Able to collapse
12.2 Purchase Requisitions and Price Quotes

The team does not have any purchase order forms for the One Arm Drive Manual Wheelchair. The team went to NEAT Marketplace and purchased a wheelchair frame and One Arm Drive system, along with head rest, foot rests, hip guides, and safety harness. This totaled to $125. There is no receipt on file for this purchase.

12.3 Related Links

The following are related links that show more information about the Invacare CLD mechanism:

- Invacare CLD Product information:  

- Invacare CLD Product Manual:  

- Video demonstrating use of CLD system:  
  [http://www.youtube.com/watch?v=eGkV5apxcvs](http://www.youtube.com/watch?v=eGkV5apxcvs)

- Local Invacare vendors:  
  [http://www.invacare/cgi-bin/imhqprd/inv_dealer/dealer_results.jsp?s=0](http://www.invacare/cgi-bin/imhqprd/inv_dealer/dealer_results.jsp?s=0)

- Invacare CLD system for sale online:  